

ROS Meetup 23.01.2024 – FZI Karlsruhe

| Speaker | | Titel |
|---------|-----------------------|--|
| 13:00 | | Arrival / Coffee |
| 13:30 | Tristan Schnell | Modular Scalable Autonomy - Advanced Robot Operations in Complex Scenarios |
| 13:50 | Michel Albonico | ML4GreenROS: A Machine Learning Approach for Optimizing the Energy Efficiency of Highly-configurable ROS Systems |
| 14:10 | Stefan Scherzinger | Using Tensorflow inside a ROS2-controller: A case study |
| 14:30 | Sebastian Jahr | Online Motion Planning with MoveIt 2 |
| 14:40 | Albert Schotschneider | TAF-BW: Enhancing Automated and Connected Driving through Smart Infrastructure |
| 14:50 | Sven Ochs | CoCar NextGen: Everything you'll ever need for Autonomous Driving |
| 15:00 | | Lab Tour |
| 16:00 | | Coffee and Networking |
| 17:00 | | End of Meeting |