

Speaker		Titel
13:00		Arrival / Coffee
13:30	Tristan Schnell	Modular Scalable Autonomy - Advanced Robot Operations in Complex Scenarios
13:50	Michel Albonico	ML4GreenROS: A Machine Learning Approach for Optimizing the Energy Efficiency of Highly-configurable ROS Systems
14:10	Stefan Scherzinger	Using Tensorflow inside a ROS2-controller: A case study
14:30		Coffee break
14:45	Christian Henkel	Towards Formal Verification in ROS Using Model Checking
14:55	Sebastian Jahr	Online Motion Planning with MoveIt 2
15:15	Albert Schotschneider	TAF-BW: Enhancing Automated and Connected Driving through Smart Infrastructure
15:25	Sven Ochs	CoCar NextGen: Everything you'll ever need for Autonomous Driving
15:35		Coffee break
15:45		Lab Tour
16:30		Coffee and Networking
17:00		End of Meeting

